

Chapter 16

1. a. $Z_T = R \parallel X_L = \frac{(1 \text{ k}\Omega \angle 0^\circ)(4 \text{ k}\Omega \angle 90^\circ)}{1 \text{ k}\Omega + j4 \text{ k}\Omega} = 970.87 \Omega \angle 14.04^\circ = 941.87 \Omega + j235.53 \Omega$

b.
$$\begin{aligned} \frac{1}{Z_T} &= \frac{1}{X_L} + \frac{1}{X_C} + \frac{1}{R} = \frac{1}{20 \text{ k}\Omega \angle 90^\circ} + \frac{1}{12 \text{ k}\Omega \angle -90^\circ} + \frac{1}{6 \text{ k}\Omega \angle 0^\circ} \\ &= 50 \times 10^{-6} \angle -90^\circ + 83.33 \times 10^{-6} \angle 90^\circ + 166.67 \times 10^{-6} \angle 0^\circ \\ &= -j50 \times 10^{-6} + j83.33 \times 10^{-6} + 166.67 \times 10^{-6} \\ &= 166.67 \times 10^{-6} + j33.33 \times 10^{-6} \\ &= 169.97 \times 10^{-6} \angle 11.31^\circ \\ Z_T &= \frac{1}{169.97 \times 10^{-6} \angle 11.31^\circ} = 5.88 \text{ k}\Omega \angle -11.31^\circ = 5.77 \text{ k}\Omega - j1.15 \text{ k}\Omega \end{aligned}$$

c. $40 \text{ mH} \parallel 20 \text{ mH} = 13.33 \text{ mH}$
 $X_L = \omega L = 2\pi fL = 2\pi(10 \text{ kHz})(13.33 \text{ mH}) = 837.55 \Omega$
 $X_C = \frac{1}{\omega C} = \frac{1}{2\pi fC} = \frac{1}{2\pi(10 \text{ kHz})(6 \text{ nF})} = 2.65 \text{ k}\Omega$
 $Z_T = X_L \parallel X_C = \frac{(837.55 \Omega \angle 90^\circ)(2.65 \text{ k}\Omega \angle -90^\circ)}{j837.55 \Omega - j2.65 \text{ k}\Omega}$
 $= 1.23 \text{ k}\Omega \angle 90^\circ = j1.23 \text{ k}\Omega$

2. a.
$$\begin{aligned} \frac{1}{Z_T} &= \frac{1}{X_L} + \frac{1}{X_C} + \frac{1}{R} = \frac{1}{8 \Omega \angle 90^\circ} + \frac{1}{4 \Omega \angle -90^\circ} + \frac{1}{12 \Omega \angle 0^\circ} \\ &= 0.125 \angle -90^\circ + 0.25 \angle 90^\circ + 0.083 \angle 0^\circ \\ &= -j0.125 + j0.25 + 0.083 \\ &= 0.083 + j0.125 = 150.05 \times 10^{-3} \angle 56.416^\circ \\ Z_T &= \frac{1}{150.05 \times 10^{-3} \angle 56.416^\circ} = 6.66 \Omega \angle -56.42^\circ = 3.68 \Omega - j5.55 \Omega \end{aligned}$$

b. $Z_T = -j4 \text{ k}\Omega = 4 \text{ k}\Omega \angle -90^\circ$

c.
$$\begin{aligned} \frac{1}{Z_T} &= \frac{1}{R_1} + \frac{1}{X_L} + \frac{1}{X_C} + \frac{1}{R_2} = \frac{1}{1.2 \text{ k}\Omega \angle 0^\circ} + \frac{1}{3.2 \text{ k}\Omega \angle 90^\circ} + \frac{1}{4.6 \text{ k}\Omega \angle -90^\circ} + \frac{1}{3.6 \text{ k}\Omega \angle 0^\circ} \\ &= 833.33 \times 10^{-6} \angle 0^\circ + 312.5 \times 10^{-6} \angle -90^\circ + 217.39 \times 10^{-6} \angle 90^\circ + 277.78 \times 10^{-6} \angle 0^\circ \\ &= 1.111 \times 10^{-3} - j312.5 \times 10^{-6} + j217.39 \times 10^{-6} \\ &= 1.111 \times 10^{-3} - j95.11 \times 10^{-6} = 1.115 \times 10^{-3} \angle -4.89^\circ \\ Z_T &= \frac{1}{1.115 \times 10^{-3} \angle -4.89^\circ} = 896.86 \Omega \angle 4.89^\circ = 893.6 \Omega + j76.45 \Omega \end{aligned}$$

3. I. $Y_T = \frac{1}{R} \angle 0^\circ = \frac{1}{6.8 \Omega} \angle 0^\circ = 147.06 \text{ mS} \angle 0^\circ = 147.06 \text{ mS}$

II. $Y_T = \frac{1}{X_L \angle 90^\circ} = \frac{1}{2 \text{ k}\Omega} \angle -90^\circ = 5 \text{ mS} \angle -90^\circ = -j5 \text{ mS}$

- III. $Y_T = \frac{1}{Z_T} = \frac{1}{X_C \angle -90^\circ} = \frac{1}{2 \text{ k}\Omega} = \angle 90^\circ = 500 \mu\text{S} \angle 90^\circ = j500 \mu\text{S}$
4. I. a. $Z_T = \frac{(10 \Omega \angle 0^\circ)(60 \Omega \angle 90^\circ)}{10 \Omega + j60 \Omega} = 9.86 \Omega \angle 9.46^\circ$
- b. $Y_T = \frac{1}{Z_T} = \frac{1}{9.86 \Omega \angle 9.46^\circ} = 0.10 \text{ S} \angle -9.46^\circ$
- c. $0.10 \text{ S} \angle -9.46^\circ = 0.1 \text{ S} - j0.02 \text{ S} = G - jB_L$
 $G = 0.1 \text{ S}$
 $B_L = 0.02 \text{ S}$
- d. –
- II. a. $22 \Omega \parallel 2.2 \Omega = 2 \Omega$
- $Z_T = \frac{(2 \Omega \angle 0^\circ)(6 \Omega \angle -90^\circ)}{2 \Omega - j6 \Omega} = \frac{12 \Omega \angle -90^\circ}{6.32 \Omega \angle -71.57^\circ} = 1.90 \Omega \angle -18.43^\circ$
- b. $Y_T = \frac{1}{Z_T} = \frac{1}{1.90 \Omega \angle -18.43^\circ} = 0.53 \text{ S} \angle 18.43^\circ$
- c. $0.53 \text{ S} \angle 18.43^\circ = 0.5 \text{ S} - j0.17 \text{ S} = G + jB_C$
 $G = 0.5 \text{ S}$
 $B_C = 0.17 \text{ S}$
- III. a. $\frac{1}{Z_T} = \frac{1}{3 \text{ k}\Omega \angle 0^\circ} + \frac{1}{6 \text{ k}\Omega \angle 90^\circ} + \frac{1}{9 \text{ k}\Omega \angle -90^\circ}$
 $= 0.333 \times 10^{-3} \angle 0^\circ + 0.167 \times 10^{-3} \angle -90^\circ + 0.111 \times 10^{-3} \angle 90^\circ$
 $= 0.333 \times 10^{-3} - j0.056 \times 10^{-3}$
 $= 0.34 \times 10^{-3} \angle -9.55^\circ$
- $Z_T = \frac{1}{0.34 \times 10^{-3} \angle -9.55^\circ} = 2.94 \text{ k}\Omega \angle 9.55^\circ$
- b. $Y_T = \frac{1}{Z_T} = \frac{1}{2.94 \text{ k}\Omega \angle 9.55^\circ} = 0.34 \text{ mS} \angle -9.55^\circ$
- c. $0.34 \text{ mS} \angle -9.55^\circ = 0.333 \times 10^{-3} \text{ S} - j0.056 \times 10^{-3} \text{ S} = G - jB_L$
 $G = 0.333 \text{ mS}$
 $B_L = 0.056 \text{ mS}$
5. I. a. $Z_T = 4.7 \Omega + j8 \Omega = 9.28 \Omega \angle 59.57^\circ$
- b. $Y_T = \frac{1}{Z_T} = \frac{1}{9.28 \text{ k}\Omega \angle 59.57^\circ} = 0.108 \text{ S} \angle -59.57^\circ$
- c. $0.108 \text{ S} \angle -54.57^\circ = 54.7 \text{ mS} - j93.12 \text{ mS} = G - jB_L$

$$G = 54.7 \text{ mS}$$

$$B_L = 93.12 \text{ mS}$$

II. a. $Z_T = 33 \Omega + 20 \Omega - j70 \Omega = 53 \Omega - j70 \Omega = 87.80 \Omega \angle -52.87^\circ$

b. $Y_T = \frac{1}{87.80 \Omega \angle -52.87^\circ} = 11.39 \text{ mS} \angle 52.87^\circ$

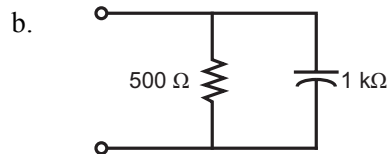
c. $11.39 \text{ mS} \angle 52.87^\circ = 6.88 \text{ mS} + j9.08 \text{ mS} = G + jB_C$
 $G = 6.88 \text{ mS}$
 $B_C = 9.08 \text{ mS}$

III. a. $Z_T = 200 \Omega + j500 \Omega - j600 \Omega = 200 \Omega - j100 \Omega = 223.61 \Omega \angle -26.57^\circ$

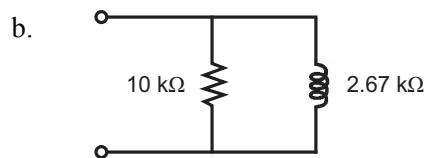
b. $Y_T = \frac{1}{223.61 \Omega \angle -26.57^\circ} = 4.47 \text{ mS} \angle 26.57^\circ$

c. $4.47 \text{ mS} \angle 26.57^\circ = 4 \text{ mS} + j2 \text{ mS} = G - jB_C$
 $G = 4 \text{ mS}$
 $B_C = 2 \text{ mS}$

6. I. a. $R_1 \parallel R_2 = \frac{1 \text{ k}\Omega}{2} = 500 \Omega$
 $X_{C_1} \parallel X_{C_2} = \frac{2 \text{ k}\Omega \angle -90^\circ}{2} = 1 \text{ k}\Omega \angle -90^\circ$
 $Y_T = \frac{1}{500 \Omega \angle 0^\circ} + \frac{1}{1 \text{ k}\Omega \angle -90^\circ}$
 $= 2 \times 10^{-3} \text{ S} + 1 \times 10^{-3} \text{ S} \angle 90^\circ$
 $= 2 \text{ mS} + j1 \text{ mS}$



II. a. $Y_T = \frac{1}{10 \text{ k}\Omega \angle 0^\circ} + \frac{1}{4 \text{ k}\Omega \angle 90^\circ} + \frac{1}{8 \text{ k}\Omega \angle 90^\circ}$
 $= 100 \times 10^{-6} + 250 \times 10^{-6} \angle -90^\circ + 125 \times 10^{-6} \angle -90^\circ$
 $= 100 \times 10^{-6} + 375 \times 10^{-6} \angle -90^\circ$
 $= 100 \mu\text{S} - j375 \mu\text{S}$

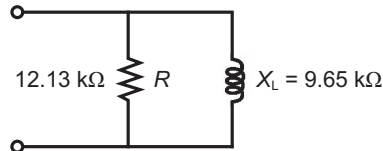


7. a. $X_L = 2\pi fL = 2\pi(2 \text{ kHz})(470 \text{ mH}) = 5.91 \text{ k}\Omega$
 $Z_T = 4.7 \text{ k}\Omega + j5.91 \text{ k}\Omega = 7.55 \text{ k}\Omega \angle 51.51^\circ$

$$\begin{aligned} Y_T &= \frac{1}{Z_T} = \frac{1}{7.55 \text{ k}\Omega \angle 51.51^\circ} = 132.45 \mu\text{S} \angle -51.51^\circ \\ &= 82.43 \mu\text{S} - j103.67 \mu\text{S} = G - jB_L \end{aligned}$$

b. $G = 82.43 \text{ mS} = \frac{1}{R} \Rightarrow R = \frac{1}{82.43 \text{ mS}} = 12.13 \text{ k}\Omega$

$$B_L = 103.67 \mu\text{S} = \frac{1}{X_L} \Rightarrow X_L = \frac{1}{103.67 \mu\text{S}} = 9.65 \text{ k}\Omega$$



c. $R = 12.13 \text{ k}\Omega$

$$X_L = 2\pi fL = 9.65 \text{ k}\Omega, L = \frac{9.65 \text{ k}\Omega}{2\pi(2 \text{ kHz})} = 767.92 \text{ mH}$$

d. Both have resistance and inductive components.

8. $Z_T = \frac{V}{I}, V = (0.7071)(24 \text{ V}) \angle -40^\circ = 16.97 \text{ V} \angle -40^\circ$

$$I = (0.7071)(6 \text{ mA}) \angle 30^\circ = 4.243 \text{ mA} \angle 30^\circ$$

$$Z_T = \frac{16.97 \text{ V} \angle -40^\circ}{4.243 \text{ mA} \angle 30^\circ} = 4 \text{ k}\Omega \angle -70^\circ$$

$$\begin{aligned} Y_T &= \frac{1}{Z_T} = \frac{1}{4 \text{ k}\Omega \angle -70^\circ} = 250 \times 10^{-6} \text{ S} \angle 70^\circ \\ &= 85.51 \times 10^{-6} \text{ S} + j234.92 \times 10^{-6} = G + jB_C \end{aligned}$$

$$G = \frac{1}{R} \Rightarrow R = \frac{1}{85.51 \times 10^{-6} \text{ S}} = 11.69 \text{ k}\Omega$$

$$B_C = \frac{1}{X_C} \Rightarrow \frac{1}{234.92 \times 10^{-6} \text{ S}} = 4.26 \text{ k}\Omega$$

$$X_C = \frac{1}{\omega C} \Rightarrow C = \frac{1}{\omega X_C} = \frac{1}{(10,000 \text{ rad/s})(4.26 \text{ k}\Omega)}$$

$$C = 23.47 \text{ nF}$$

9. a. $Y_T = \frac{1}{10 \Omega \angle 0^\circ} + \frac{1}{20 \Omega \angle 90^\circ} = 0.1 \text{ S} - j0.05 \text{ S} = 111.8 \text{ mS} \angle -26.57^\circ$

b. -

c. $E = I_s / Y_T = 2 \text{ A} \angle 0^\circ / 111.8 \text{ mS} \angle -26.57^\circ = 17.89 \text{ V} \angle 26.57^\circ$

$$I_R = \frac{E \angle \theta}{R \angle 0^\circ} = 17.89 \text{ V} \angle 26.57^\circ / 10 \Omega \angle 0^\circ = 1.79 \text{ A} \angle 26.57^\circ$$

$$\mathbf{I}_L = \frac{E \angle \theta}{X_L \angle 90^\circ} = 17.89 \text{ V } \angle 26.57^\circ / 20 \text{ } \Omega \angle 90^\circ = \mathbf{0.89 \text{ A } \angle -63.43^\circ}$$

f. $P = I^2 R = (1.79 \text{ A})^2 10 \text{ } \Omega = \mathbf{32.04 \text{ W}}$

g. $F_p = \frac{G}{Y_T} = \frac{0.1 \text{ S}}{111.8 \text{ mS}} = \mathbf{0.894 \text{ lagging}}$

h. $e = \mathbf{25.30 \sin(377t + 26.57^\circ)}$
 $i_R = \mathbf{2.53 \sin(377t + 26.57^\circ)}$
 $i_L = \mathbf{1.26 \sin(377t - 63.43^\circ)}$
 $i_s = \mathbf{2.83 \sin 377t}$

10. a. $X_C = \frac{1}{2\pi fC} = \frac{1}{2\pi (60 \text{ Hz})(0.13 \text{ } \mu\text{F})} = 20.4 \text{ k}\Omega$

b. $\mathbf{Y_T} = \frac{1}{10 \text{ k}\Omega \angle 0^\circ} + \frac{1}{20.4 \text{ k}\Omega \angle -90^\circ} = 0.1 \text{ mS } \angle 0^\circ + 0.049 \text{ mS } \angle -90^\circ$
 $= \mathbf{0.111 \text{ mS } \angle 26.10^\circ}$

c. $\mathbf{E} = \frac{\mathbf{I}_s}{\mathbf{Y_T}} = \frac{2 \text{ mA } \angle 20^\circ}{0.111 \text{ mS } \angle 26.10^\circ} = \mathbf{18.02 \text{ V } \angle -6.1^\circ}$
 $\mathbf{I}_R = \frac{\mathbf{E}}{\mathbf{Z}_R} = \frac{18.02 \text{ V } \angle -6.1^\circ}{10 \text{ k}\Omega \angle 0^\circ} = \mathbf{1.80 \text{ mA } \angle -6.1^\circ}$
 $\mathbf{I}_C = \frac{\mathbf{E}}{\mathbf{Z}_C} = \frac{18.02 \text{ V } \angle -6.1^\circ}{20.4 \text{ k}\Omega \angle -90^\circ} = \mathbf{0.883 \text{ mA } \angle 83.90^\circ}$

d. —

e. $\mathbf{I}_s = \mathbf{I}_R + \mathbf{I}_C$
 $2 \text{ mA } \angle 20^\circ = 1.80 \text{ mA } \angle -6.1^\circ + 0.883 \text{ mA } \angle 83.90^\circ$
 $= (1.79 \text{ mA} - j0.191 \text{ mA}) + (0.094 \text{ mA} + j0.878 \text{ mA})$
 $= 1.88 \text{ mA} + j0.687 \text{ mA}$
 $2 \text{ mA } \angle 20^\circ \cong 2 \text{ mA } \angle 20.07^\circ$

f. $P = I^2 R = (1.80 \text{ mA})^2 10 \text{ k}\Omega = \mathbf{32.4 \text{ mW}}$

g. $F_p = \frac{G}{Y_T} = \frac{0.1 \text{ mS}}{0.111 \text{ mS}} = \mathbf{0.9 \text{ leading}}$

h. $\omega = 2\pi f = 377 \text{ rad/s}$
 $i_s = \mathbf{2.83 \times 10^{-3} \sin(\omega t + 20^\circ)}$
 $i_R = \mathbf{2.55 \times 10^{-3} \sin(\omega t - 6.57^\circ)}$
 $i_C = \mathbf{1.25 \times 10^{-3} \sin(\omega t + 83.44^\circ)}$
 $e = \mathbf{25.48 \sin(\omega t - 6.57^\circ)}$

11. a. $R_1 \parallel R_2 = 220 \text{ } \Omega \parallel 120 \text{ } \Omega = 77.65 \text{ } \Omega$

$$\begin{aligned} \mathbf{X}_C \parallel \mathbf{X}_L &= 60 \Omega \angle -90^\circ \parallel 40 \Omega \angle 90^\circ \\ &= \frac{2400 \angle 0^\circ}{-j60 + j40} = \frac{2400 \angle 0^\circ}{-j20} = \frac{2400 \angle 0^\circ}{20 \angle -90^\circ} = 120 \Omega \angle 90^\circ \end{aligned}$$

$$\begin{aligned} \mathbf{Z}_T &= (R_1 \parallel R_2) \parallel (\mathbf{X}_C \parallel \mathbf{X}_L) \\ &= 77.65 \Omega \angle 0^\circ \parallel 120 \Omega \angle 90^\circ \\ &= \frac{(77.65)(120) \angle 90^\circ}{77.65 + j120} = \frac{9.32 \times 10^3 \angle 90^\circ}{142.93 \angle 57.09^\circ} = \mathbf{65.21 \Omega \angle 32.91^\circ} \end{aligned}$$

b. $\mathbf{Y}_T = \frac{1}{\mathbf{Z}_T} = \frac{1}{65.21 \Omega \angle 32.91^\circ} = \mathbf{15.34 \text{ mS} \angle -32.91^\circ}$

c. -

d. $\mathbf{I}_s = \frac{\mathbf{E}}{\mathbf{Z}_T} = \frac{12 \text{ V} \angle 0^\circ}{65.21 \Omega \angle 32.91^\circ} = \mathbf{184.02 \text{ mA} \angle -32.91^\circ}$

e. $\mathbf{I}_C = \frac{\mathbf{E}}{\mathbf{X}_C} = \frac{12 \text{ V} \angle 0^\circ}{60 \Omega \angle -90^\circ} = \mathbf{200 \text{ mA} \angle 90^\circ}$

f. $e = (1.414)(12) \sin \omega t = \mathbf{16.97 \sin \omega t}$
 $i_s = (1.414)(184.02 \times 10^{-3}) \sin(\omega t - 32.91^\circ)$
 $= \mathbf{260.02 \times 10^{-3} \sin(\omega t - 32.91^\circ)}$

g. $F_p = \cos \theta_T = \cos 32.91^\circ = \mathbf{0.84 \text{ lagging}}$

12. a. $\mathbf{Y}_T = \frac{1}{1.2 \Omega \angle 0^\circ} + \frac{1}{2 \Omega \angle 90^\circ} + \frac{1}{5 \Omega \angle -90^\circ}$
 $= 0.833 \text{ S} \angle 0^\circ + 0.5 \text{ S} \angle -90^\circ + 0.2 \text{ S} \angle 90^\circ$
 $= 0.833 \text{ S} - j0.3 \text{ S} = \mathbf{0.89 \text{ S} \angle -19.81^\circ}$
 $\mathbf{Z}_T = \mathbf{1.12 \Omega \angle 19.81^\circ}$

b. -

c. $X_C = \frac{1}{\omega C} \Rightarrow C = \frac{1}{\omega X_C} = \frac{1}{(377 \text{ rad/s})(5 \Omega)} = \mathbf{531 \mu\text{F}}$

$$X_L = \omega L \Rightarrow L = \frac{X_L}{\omega} = \frac{2 \Omega}{377 \text{ rad/s}} = \mathbf{5.31 \text{ mH}}$$

d. $\mathbf{E} = \frac{\mathbf{I}_s}{\mathbf{Y}_T} = \frac{(0.707)(3 \text{ A}) \angle 60^\circ}{0.885 \text{ S} \angle -19.81^\circ} = \frac{2.121 \text{ A} \angle 60^\circ}{0.885 \text{ S} \angle -19.81^\circ} = \mathbf{2.40 \text{ V} \angle 79.81^\circ}$

$$\mathbf{I}_R = \frac{E \angle \theta}{R \angle 0^\circ} = \frac{2.397 \text{ V} \angle 79.81^\circ}{1.2 \Omega \angle 0^\circ} = \mathbf{2.00 \text{ A} \angle 79.81^\circ}$$

$$\mathbf{I}_L = \frac{E \angle \theta}{X_L \angle 90^\circ} = \frac{2.397 \text{ V} \angle 79.81^\circ}{2 \Omega \angle 90^\circ} = \mathbf{1.20 \text{ A} \angle -10.19^\circ}$$

$$\mathbf{I}_C = \frac{E \angle \theta}{X_C \angle -90^\circ} = \frac{2.397 \text{ V} \angle 79.81^\circ}{5 \Omega \angle -90^\circ} = \mathbf{0.48 \text{ A} \angle 169.81^\circ}$$

f. $\mathbf{I}_s = \mathbf{I}_R + \mathbf{I}_L + \mathbf{I}_C$
 $2.121 \text{ A} \angle 60^\circ = 2.00 \text{ A} \angle 79.81^\circ + 1.20 \text{ A} \angle -10.19^\circ + 0.48 \text{ A} \angle 169.81^\circ$
 $2.121 \text{ A} \angle 60^\circ \checkmark = 2.13 \text{ A} \angle 60.01^\circ$

g. $P = I^2 R = (2.00 \text{ A})^2 1.2 \Omega = \mathbf{4.8 \text{ W}}$

h. $F_p = \frac{G}{Y_T} = \frac{0.833 \text{ S}}{0.885 \text{ S}} = \mathbf{0.941 \text{ lagging}}$

i. $e = \mathbf{3.39 \sin(377t + 79.81^\circ)}$
 $i_R = \mathbf{2.83 \sin(377t + 79.81^\circ)}$
 $i_L = \mathbf{1.70 \sin(377t - 10.19^\circ)}$
 $i_C = \mathbf{0.68 \sin(377t + 169.81^\circ)}$

13. a. $X_L = \omega L = (1000 \text{ rad/s})(3.9 \text{ H}) = 3.9 \text{ k}\Omega$,
 $X_C = \frac{1}{\omega C} = \frac{1}{(1000 \text{ rad/s})(0.12 \mu\text{F})} = 8.33 \text{ k}\Omega$

$$\mathbf{Y}_T = \frac{1}{3 \text{ k}\Omega \angle 0^\circ} + \frac{1}{3.9 \text{ k}\Omega \angle 90^\circ} + \frac{1}{8.33 \text{ k}\Omega \angle -90^\circ}$$

$$= 0.333 \text{ mS} \angle 0^\circ + 0.256 \text{ mS} \angle -90^\circ + 0.120 \text{ mS} \angle 90^\circ$$

$$= \mathbf{0.333 \text{ mS} - j0.136 \text{ mS} = 0.36 \text{ mS} \angle -22.22^\circ}$$

d. $\mathbf{E = I/Y}_T = 3.54 \text{ mA} \angle -20^\circ / 0.36 \text{ mS} \angle -22.22^\circ = \mathbf{9.83 \text{ V} \angle 2.22^\circ}$

$$\mathbf{I}_R = \frac{E \angle \theta}{R \angle 0^\circ} = 9.83 \text{ V} \angle 2.22^\circ / 3 \text{ k}\Omega \angle 0^\circ = \mathbf{3.28 \text{ mA} \angle 2.22^\circ}$$

$$\mathbf{I}_L = \frac{E \angle \theta}{X_L \angle 90^\circ} = 9.83 \text{ V} \angle 2.22^\circ / 3.9 \text{ k}\Omega \angle 90^\circ = \mathbf{2.52 \text{ mA} \angle -87.78^\circ}$$

$$\mathbf{I}_C = \frac{E \angle \theta}{X_C \angle -90^\circ} = 9.83 \text{ V} \angle 2.22^\circ / 8.33 \text{ k}\Omega \angle -90^\circ = \mathbf{1.18 \text{ mA} \angle 92.22^\circ}$$

g. $P = I^2 R = (3.28 \text{ mA})^2 3 \text{ k}\Omega = \mathbf{32.28 \text{ mW}}$

h. $F_p = G/Y_T = 0.333 \text{ mS} / 0.36 \text{ mS} = \mathbf{0.925 \text{ leading}}$

i. $e = \mathbf{13.9 \sin(1000t + 2.22^\circ)}$
 $i_R \cong \mathbf{4.64 \times 10^{-3} \sin(1000t + 2.22^\circ)}$
 $i_L \cong \mathbf{3.56 \times 10^{-3} \sin(1000t - 87.78^\circ)}$
 $i_C \cong \mathbf{1.67 \times 10^{-3} \sin(1000t + 92.22^\circ)}$

14. a. $\mathbf{I}_1 = \frac{(60 \Omega \angle 90^\circ)(20 \text{ A} \angle 40^\circ)}{22 \Omega + j60 \Omega} = \frac{120 \text{ A} \angle 130^\circ}{63.91 \angle 69.86^\circ} = \mathbf{18.78 \angle 60.14^\circ}$

$$\mathbf{I}_2 = \frac{(22 \Omega \angle 0^\circ)(20 \text{ A} \angle 40^\circ)}{63.91 \Omega \angle 69.86^\circ} = \frac{440 \text{ A} \angle 40^\circ}{63.91 \angle 69.86^\circ} = \mathbf{6.88 \angle -29.86^\circ}$$

$$\begin{aligned} \text{b. } \mathbf{I}_1 &= \frac{(12 \Omega - j6 \Omega)(6 \text{ A} \angle 30^\circ)}{12 \Omega - j6 \Omega + j4 \Omega} = \frac{(13.42 \angle -26.57^\circ)(6 \text{ A} \angle 30^\circ)}{12 - j2} \\ &= \frac{80.52 \text{ A} \angle 3.43^\circ}{12.17 \angle -9.46^\circ} = \mathbf{6.62 \text{ A} \angle 12.89^\circ} \end{aligned}$$

$$\mathbf{I}_2 = \frac{(4 \Omega \angle 90^\circ)(6 \text{ A} \angle 30^\circ)}{12.17 \angle -9.46^\circ} = \frac{24 \text{ A} \angle 120^\circ}{12.17 \angle -9.46^\circ} = \mathbf{1.97 \text{ A} \angle 129.46^\circ}$$

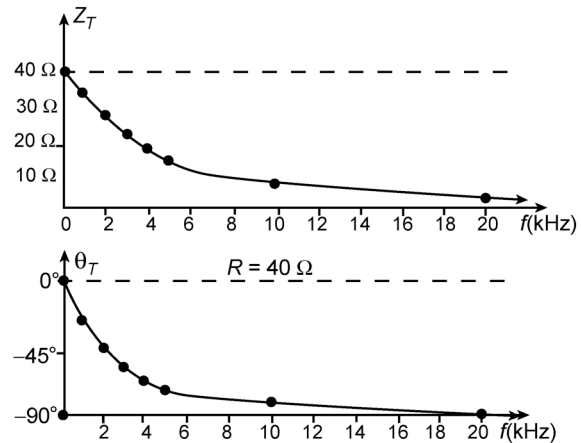
$$\begin{aligned} \text{c. } \mathbf{I}_1 &= \frac{(-j10 \Omega + j40 \Omega)(4 \text{ A} \angle 0^\circ)}{+j20 \Omega - j10 \Omega + j40 \Omega} = \frac{(30 \Omega \angle 90^\circ)(4 \text{ A} \angle 0^\circ)}{50 \Omega \angle 90^\circ} \\ &= \mathbf{2.4 \text{ A} \angle 0^\circ} \end{aligned}$$

$$\mathbf{I}_2 = \frac{(20 \Omega \angle 90^\circ)(4 \text{ A} \angle 0^\circ)}{50 \Omega \angle 90^\circ} = \mathbf{1.6 \text{ A} \angle 0^\circ}$$

$$15. \text{ a. } \mathbf{Z}_T = \frac{(R \angle 0^\circ)(X_C \angle -90^\circ)}{R - jX_C} = \frac{RX_C}{\sqrt{R^2 + X_C^2}} \angle -90^\circ + \tan^{-1} X_C/R$$

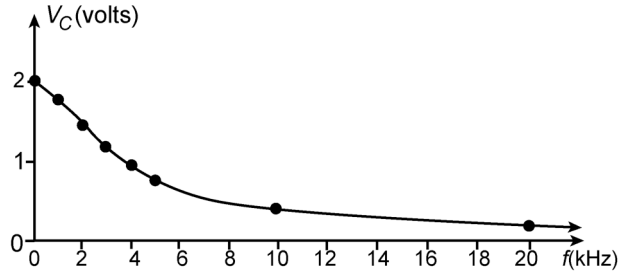
$$|Z_T| = \frac{RX_C}{\sqrt{R^2 + X_C^2}} \quad \theta_T = -90^\circ + \tan^{-1} X_C/R$$

f	$ Z_T $	θ_T
0 Hz	40.0	0.0°
1 kHz	35.74	-26.67°
2 kHz	28.22	-45.14°
3 kHz	22.11	-56.44°
4 kHz	17.82	-63.55°
5 kHz	14.79	-68.30°
10 kHz	7.81	-78.75°
20 kHz	3.959	-89.86°



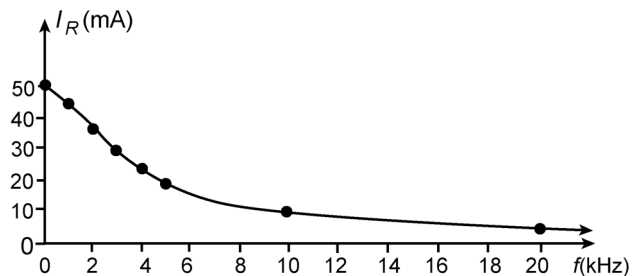
$$\text{b. } |V_C| = \frac{IRX_C}{\sqrt{R^2 + X_C^2}} = I[Z_T(f)]$$

f	$ V_C $
0 kHz	2.0 V
1 kHz	1.787 V
2 kHz	1.411 V
3 kHz	1.105 V
4 kHz	0.891 V
5 kHz	0.740 V
10 kHz	0.391 V
20 kHz	0.198 V



c. $|I_R| = \left| \frac{V_C}{R} \right|$

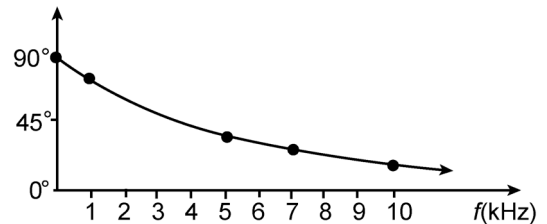
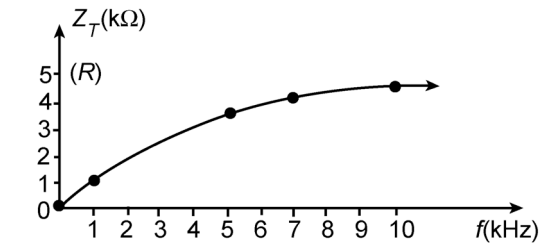
f	$ I_R $
0 kHz	50.0 mA
1 kHz	44.7 mA
2 kHz	35.3 mA
3 kHz	27.64 mA
4 kHz	22.28 mA
5 kHz	18.50 mA
10 kHz	9.78 mA
20 kHz	4.95 mA



16. a. $\mathbf{Z}_T = \frac{\mathbf{Z}_R \mathbf{Z}_L}{\mathbf{Z}_R + \mathbf{Z}_L} = \frac{(R \angle 0^\circ)(X_L \angle 90^\circ)}{R + jX_L} = \frac{RX_L}{\sqrt{R^2 + X_L^2}} \angle 90^\circ - \tan^{-1} X_L/R$

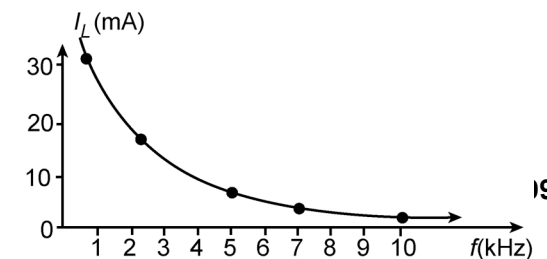
$$|Z_T| = \frac{RX_L}{\sqrt{R^2 + X_L^2}} \quad \theta_T = 90^\circ - \tan^{-1} X_L/R$$

f	$ Z_T $	θ_T
0 Hz	0.0 k	90.0°
1 kHz	1.22 k	75.86°
5 kHz	3.91 k	38.53°
7 kHz	4.35 k	29.6°
10 kHz	4.65 k	21.69°



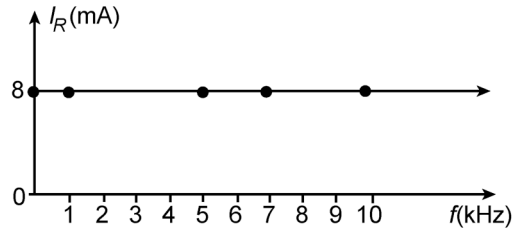
b. $|I_L| = \frac{E}{X_L}$

f	$ I_L $
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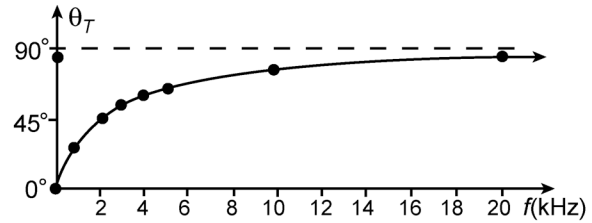
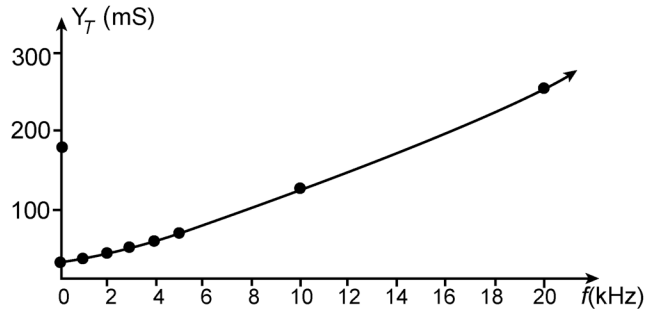
0 Hz	∞
1 kHz	31.75 mA
5 kHz	6.37 mA
7 kHz	4.55 mA
10 kHz	3.18 mA

c. $I_R = \frac{E}{R} = \frac{40 \text{ V}}{5 \text{ k}\Omega} = 8 \text{ mA (constant)}$



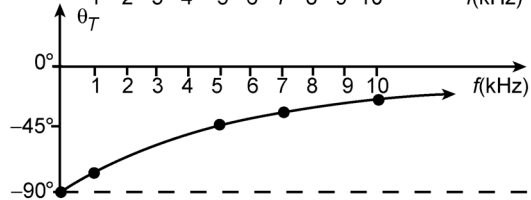
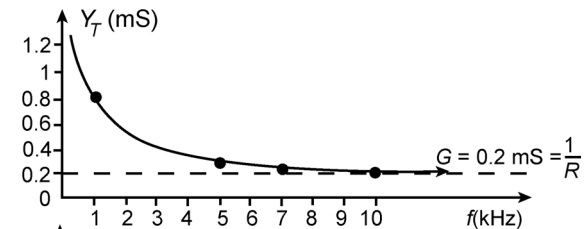
17. $Y_T = \frac{\sqrt{R^2 + X_C^2}}{RX_C} \angle 90^\circ - \tan^{-1} X_C/R$

f	Y_T	θ_T
0 Hz	25.0 mS	0.0°
1 kHz	27.98 mS	26.67°
2 kHz	35.44 mS	45.14°
3 kHz	45.23 mS	56.44°
4 kHz	56.12 mS	63.55°
5 kHz	67.61 mS	68.30°
10 kHz	128.04 mS	78.75°
20 kHz	252.59 mS	89.86°



18. $Y_T = \frac{1}{Z_T}$ (use data of Prob. 36), $\theta_{T_Y} = -\theta_{T_Z}$

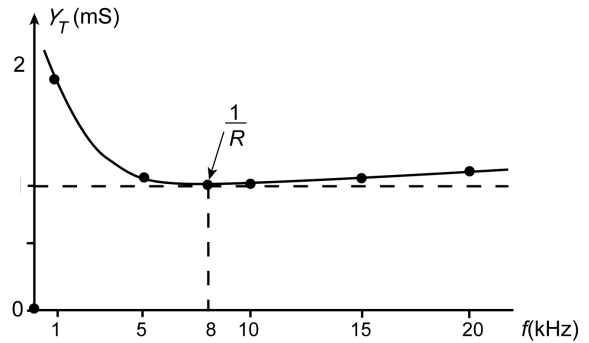
f	Y_T	θ_T
0 Hz	∞	-90.0°
1 kHz	0.82 mS	-75.86°
5 kHz	0.256 mS	-38.53°
7 kHz	0.23 mS	-29.6°
10 kHz	0.215 mS	-21.69°



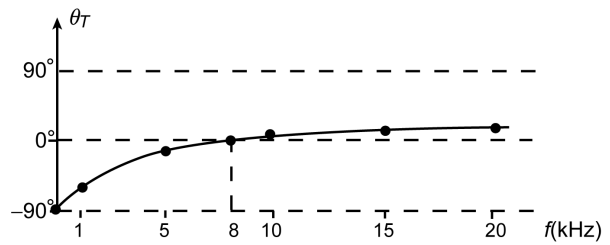
19. a.
$$Y_T = G \angle 0^\circ + B_L \angle -90^\circ + B_C \angle 90^\circ$$

$$= \sqrt{G^2 + (B_C - B_L)^2} \angle \tan^{-1} \frac{B_C - B_L}{G}$$

f	$ Y_T $
0 Hz	$X_L \Rightarrow 0, Z_T = 0, Y_T = \infty$
1 kHz	1.86 mS
5 kHz	1.02 mS
10 kHz	1.00 mS
15 kHz	1.02 mS
20 kHz	1.04 mS

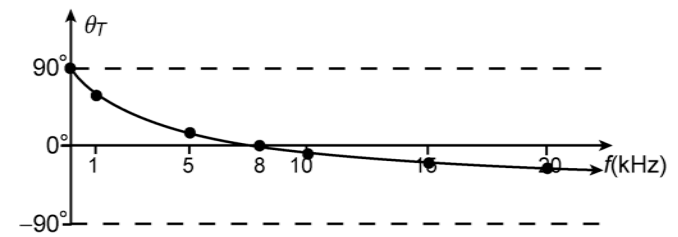
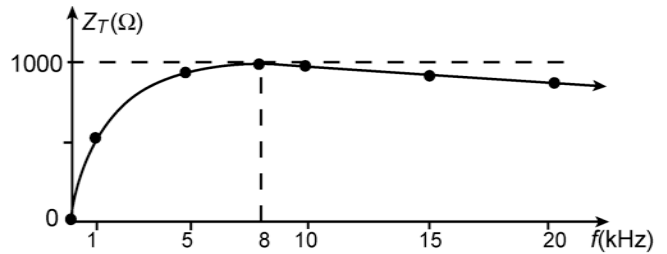


f	$ \theta_T $
0 Hz	-90.0°
1 kHz	-57.51°
5 kHz	-12.63°
10 kHz	$+1.66^\circ$
15 kHz	$+9.98^\circ$
20 kHz	$+16.54^\circ$



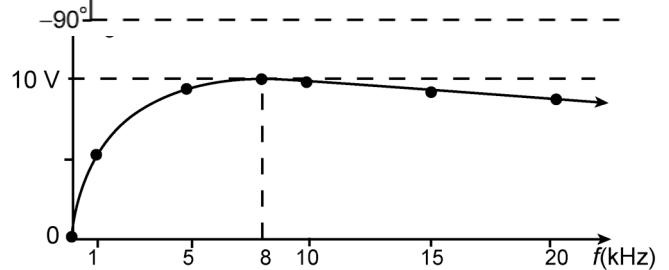
b. $Z_T = \frac{1}{Y_T}, \theta_{Tz} = -\theta_{Ty}$

f	Z_T	θ_T
0 kHz	0.0	90.0°
1 kHz	537.63	57.52°
5 kHz	980.39	12.63°
10 kHz	1 k	-1.66°
15 kHz	980.39	-9.98°
20 kHz	961.54	-16.54°



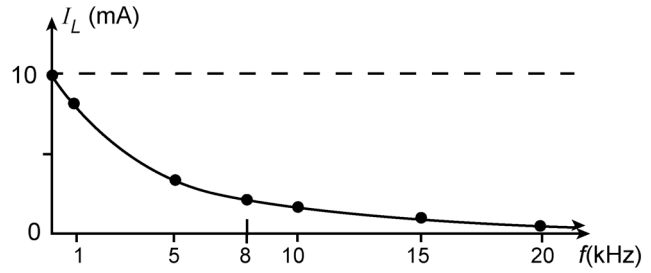
c. $V_C(f) = I[Z_T(f)]$

f	$ V_C $
0 kHz	0.0 V
1 kHz	5.38 V
5 kHz	9.80 V
10 kHz	10 V
15 kHz	9.80 V
20 kHz	9.62 V



$$d. \quad I_L = \frac{V_L(f)}{X_L} = \frac{V_C(f)}{X_L}$$

f	I_L
0 kHz	10.0 mA
1 kHz	8.56 mA
5 kHz	3.12 mA
10 kHz	1.59 mA
15 kHz	1.04 mA
20 kHz	0.765 mA



$$20. \quad a. \quad R_p = \frac{R_s^2 + X_s^2}{R_s} = \frac{(20 \Omega)^2 + (40 \Omega)^2}{20 \Omega} = \mathbf{100 \Omega (R)}$$

$$X_p = \frac{R_s^2 + X_s^2}{X_s} = \frac{2000 \Omega}{40} = \mathbf{50 \Omega (C)}$$

$$b. \quad R_p = \frac{R_s^2 + X_s^2}{R_s} = \frac{(2 \text{ k}\Omega)^2 + (8 \text{ k}\Omega)^2}{2 \text{ k}\Omega} = \mathbf{34 \text{ k}\Omega (R)}$$

$$X_p = \frac{R_s^2 + X_s^2}{X_s} = \frac{(2 \text{ k}\Omega)^2 + (8 \text{ k}\Omega)^2}{8 \text{ k}\Omega} = \mathbf{8.5 \text{ k}\Omega (L)}$$

$$21. \quad a. \quad R_s = \frac{R_p X_p^2}{X_p^2 + R_p^2} = \frac{(8.2 \text{ k}\Omega)(20 \text{ k}\Omega)^2}{(20 \text{ k}\Omega)^2 + (8.2 \text{ k}\Omega)^2} = \mathbf{7.02 \text{ k}\Omega}$$

$$X_s = \frac{R_p^2 X_p}{X_p^2 + R_p^2} = \frac{(8.2 \text{ k}\Omega)^2 (20 \text{ k}\Omega)}{467.24 \text{ k}\Omega} = \mathbf{2.88 \text{ k}\Omega}$$

$$\mathbf{Z_T = 7.02 \text{ k}\Omega - j2.88 \text{ k}\Omega}$$

$$b. \quad R_s = \frac{R_p X_p^2}{X_p^2 + R_p^2} = \frac{(68 \Omega)(40 \Omega)^2}{(40 \Omega)^2 + (68 \Omega)^2} = \mathbf{17.48 \Omega}$$

$$X_s = \frac{R_p^2 X_p}{X_p^2 + R_p^2} = \frac{(68 \Omega)^2 (40 \Omega)}{6224 \Omega^2} = \mathbf{29.72 \Omega}$$

$$\mathbf{Z_T = 17.48 \Omega + j29.72 \Omega}$$

$$22. \quad a. \quad C_T = 2 \mu\text{F}$$

$$X_C = \frac{1}{\omega C} = \frac{1}{2\pi(10^3 \text{ Hz})(2 \mu\text{F})} = 79.62 \Omega$$

$$X_L = \omega L = 2\pi(10^3 \text{ Hz})(10 \text{ mH}) = 62.8 \Omega$$

$$\mathbf{Y_T = \frac{1}{220 \Omega \angle 0^\circ} + \frac{1}{79.62 \Omega \angle -90^\circ} + \frac{1}{62.8 \Omega \angle 90^\circ}}$$

$$= 4.55 \text{ mS} \angle 0^\circ + 12.56 \text{ mS} \angle 90^\circ + 15.92 \text{ mS} \angle -90^\circ$$

$$= 4.55 \text{ mS} - j3.36 \text{ mS} = 5.66 \text{ mS} \angle -36.44^\circ$$

$$\mathbf{E} = \mathbf{I}/\mathbf{Y}_T = 1 \text{ A} \angle 0^\circ / 5.66 \text{ mS} \angle -36.44^\circ = 176.68 \text{ V} \angle 36.44^\circ$$

$$\mathbf{I}_R = \frac{\mathbf{E} \angle \theta}{R \angle 0^\circ} = 176.68 \text{ V} \angle 36.44^\circ / 220 \angle 0^\circ = 0.803 \text{ A} \angle 36.44^\circ$$

$$\mathbf{I}_L = \frac{\mathbf{E} \angle \theta}{X_L \angle 90^\circ} = 176.68 \text{ V} \angle 36.44^\circ / 62.80 \angle 90^\circ = 2.813 \text{ A} \angle -53.56^\circ$$

b. $F_p = G/Y_T = 4.55 \text{ mS} / 5.66 \text{ mS} = \mathbf{0.804 \text{ lagging}}$

c. $P = I^2 R = (0.803 \text{ A})^2 220 \Omega = \mathbf{141.86 \text{ W}}$

f. $\mathbf{I}_s = \mathbf{I}_R + 2\mathbf{I}_C + \mathbf{I}_L$
 and $\mathbf{I}_C = \frac{\mathbf{I}_s - \mathbf{I}_R - \mathbf{I}_L}{2}$

$$= \frac{1 \text{ A} \angle 0^\circ - 0.803 \text{ A} \angle 36.44^\circ - 2.813 \text{ A} \angle -53.56^\circ}{2}$$

$$= \frac{1 - (0.646 + j0.477) - (1.671 - j2.263)}{2} = \frac{-1.317 + j1.786}{2}$$

$$\mathbf{I}_C = -0.657 + j0.893 = \mathbf{1.11 \text{ A} \angle 126.43^\circ}$$

g. $\mathbf{Z}_T = \frac{1}{\mathbf{Y}_T} = \frac{1}{5.66 \text{ mS} \angle -36.44^\circ} = 176.7 \Omega \angle 36.44^\circ$

$$= \mathbf{142.15 \Omega + j104.96 \Omega} = R + jX_L$$

23. $P = VI \cos \theta = 3000 \text{ W}$

$$\cos \theta = \frac{3000 \text{ W}}{VI} = \frac{3000 \text{ W}}{(100 \text{ V})(40 \text{ A})} = \frac{3000}{4000} = 0.75 \text{ (lagging)}$$

$$\theta = \cos^{-1} 0.75 = 41.41^\circ$$

$$\mathbf{Y}_T = \frac{\mathbf{I}}{\mathbf{E}} = \frac{40 \text{ A} \angle -41.41^\circ}{100 \text{ V} \angle 0^\circ} = 0.4 \text{ S} \angle -41.41^\circ = 0.3 \text{ S} - j0.265 \text{ S} = G_T - jB_L$$

$$G_T = 0.3 \text{ S} = \frac{1}{20 \Omega} + \frac{1}{R'} = 0.05 \text{ S} + \frac{1}{R'}$$

$$\text{and } R' = \frac{1}{0.25 \text{ S}} = 4 \Omega$$

$$X_L = \frac{1}{B_L} = \frac{1}{0.265 \text{ S}} = \mathbf{3.74 \Omega}$$

